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this paper describes a mechanical system design concept and a prototype implementation of a 5 dof jointed arm robot which should perform industrial task such as pick and place operation this robot arm being controlled by a microcontroller and interfaced to a computer has base rotation shoulder elbow and wrist motion and a functional gripper

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the document discusses various topics related to robotics including 1 it explains the components and structure of a robot arm including joints links and the joint link numbering scheme 2 it discusses the four basic robot configurations classified by coordinate system cartesian cylindrical polar and joint arm 3

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