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if you look at my x11 jumper plug connection diagram in download section it is clearly stated that this is for krc1 only when one is making test jumper plug it is convenient to add that connection so that plug can be used on both krc2 and krc1 but obviously krc2 does not need it

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1 checked the complete wiring of x11 and found it correct i am sure of this because we are already using the same configuration in our other projects on krc4 controllers 2 i checked the safety configuration and it is as an attached screenshot 3

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the content of this documentation for conformity with the hardware and software described nevertheless discrepancies cannot be precluded for which reason we are not able to guarantee total conformity hardware robodk supports all kuka robot controllers since krc2 including

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