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using the definition of static equilibrium to set up equations that allow for the analysis of rigid body systems includes several worked examples equilibrium of rigid body equilibrium is a state of body where neither the internal energy nor the motion of the body changes with respect to time let us try to understand the equilibrium of a rigid body process of solving rigid body equilibrium problems 1 create idealized model modeling and assumptions 2 draw free body diagram showing all the external applied loads and supports 3 apply equations of equilibrium example 1 beam end reactions 1 label components of reactions depending on the support condition include vertical horizontal and rotational 2 convert area loads to point loads through the centroid of the area 3 since there is only one horizontal force it must equal zero this chapter will investigate the equilibrium of simple rigid bodies like your book phone or pencil the important difference between rigid bodies and the particles of chapter 3 is that rigid bodies have the potential to rotate around a point or axis while particles do not the first equilibrium condition for the static equilibrium of a rigid body expresses translational equilibrium  $\sum F_x = 0$  the first equilibrium condition equation 12.2.2 is the equilibrium condition for forces which we encountered when studying applications of Newton's laws in this chapter we will investigate the equilibrium of simple rigid bodies like your book phone or pencil the important difference between rigid bodies and the particles of chapter 3 is that rigid bodies have the potential to rotate around a point or axis while particles do not basically the equilibrium equations for rigid bodies are a way to determine unknown forces and moments using known forces and moments separating the motion in 2 or 3 directions for translation and rotation moments could be calculated because rigid bodies also consider shape and length the static equilibrium of a mechanical system rigid bodies is defined by the condition that the virtual work of the applied forces is zero for any virtual displacement of the system this is known as the principle of virtual work 5.2d rigid body equilibrium two dimensional rigid bodies have three degrees of freedom so they only require three independent equilibrium equations to solve the six scalar equations of 5.3.3 can easily be reduced to three by eliminating the equations which refer to the unused z dimension in this explainer we will learn how to solve problems about the equilibrium of rigid bodies in 2d where the sum of forces and the sum of moments equal zero if a body is rigid forces acting on it

cannot produce deformation equilibrium of rigid bodies definition equilibrium is the state when all the external forces acting on a rigid body form a system of forces equivalent to zero there will be no rotation or translation the forces are referred to as balanced rigid body equilibrium is a dynamic equilibrium of a rigid body it occurs when the net force on the rigid body is zero the equations of rigid bodies in equilibrium are derived from the combination of newton s laws of motion newton s law of universal gravitation and a set of constraints on the motion of the rigid body two dimensional rigid bodies have three degrees of freedom so they only require three independent equilibrium equations to solve the six scalar equations of 5 3 3 can easily be reduced to three by eliminating the equations which refer to the unused z dimension equal and opposite forces acting on a rigid body may act so as to compress the body figure 19a or to stretch it figure 19b the bodies are then said to be under compression or under tension respectively strings chains and cables are rigid under tension but may collapse under compression a uniform rod of mass  $m$  and length  $2a$  is held in equilibrium by a light inelastic string of length  $2a$  and by a frictional force due to the rod s contact with a rough vertical wall the angle between the string and the rod is  $60^\circ$  as shown in the diagram below statics 3d rigid body equilibrium what are the similarities and differences between solving two dimensional and three dimensional equilibrium problems why are some three dimensional reaction couple moments available but not engaged what kinds of problems are solvable using linear algebra equilibrium of rigid bodies introduction most of the objects that one sees are in a state of equilibrium that is at rest or in a state of uniform motion many man made structures are designed to achieve and sustain a state of equilibrium and this in turn sets require visit [ilectureonline.com](http://ilectureonline.com) for more math and science lectures in this video i will introduce equilibrium of rigid bodies where sum of the forces  $\Sigma F = 0$  and sum of the moments  $\Sigma M = 0$  next let s go through how to solve 3d equilibrium problems with 3 force reactions and 3 moment reactions we go through multiple examples step by step and find reactions for different supports like

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